Adaptive Adaptive Indexing

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Introduction

Till now have looked at different types of indexes in class...

What is the problem?

But our requirements are not constant

Workload, machine and user requirements are constantly changing

- Tree
 - B+ Tree
 - LSM Tree
 - Radix Tree
- Hash index
- Bitmap index

Problem Statement

How can we design an index that is able to handle these changing environment?

Manual Tuning



Adaptively build indexes

Introducing the Concept of Cracking

What does it mean to build indexes adaptively in context of workload?



Standard Cracking

• Two times crack-in-two

Pros:

- Cheapest initialization cost
- Performs very well under uniform workload



What might be the issue with technique?

Sequential Workload



What is the problem?

- Long convergence time
- Least amount of reorganization

Can we do better?

Stochastic Cracking

 Introduces random cracks on top of Standard Cracking

> Pros: Robust under various workload as it decouples reorganization from queries



Hybrid Cracking

 Split the inputs into partitions, merge the final column

 Improve convergence speed and memory footprint



Issues with existing work

Adaptive indexes already exists. Why are do we need another one?

Each of the other indexes only addresses one specific problem!

Solution to all the problems?

What if we can create a system with more adaptivity?

Adaptive Adaptive Indexing (meta-adaptivity)

Adaptive Adaptive Indexing

What do we mean by meta-adaptivity?

A system that can be extended with various implementations and can switch implementations based on user and current workload requirements.

Components of Adaptive Adaptive Indexing

Generalize Index Refinement Adapt Reorganization Effort Defuse Skewed Data

Generalize Index Refinement

The applied fan-out of a partitioning algorithm dictates the convergence speed, variance, and distribution of the indexing effort.

A system needs different implementations for adaptive indexing depending on the workload.

An algorithm that is able to set the fan-out of the partitioning procedure freely is able to adapt to the behavior of various adaptive indexing algorithms.

- K= 2 -> Standard Cracking
- K = 2^64 for 64 bit keys -> Sorting

Partition-in-K for reorganizing the index using a freely adaptive fanout

- Distiguish b/w the out of place algorithm for the 1st query, optimized inplace algorithm for the rest
- But use radix partitioning instead of comparison based methods

Problem with comparison based method?

Radix Partitioning

Radix based partitioning has a higher partitioning throughput.

| Number | Binary Form |
|--------|----------------------|
| 25 | <mark>11</mark> 001 |
| 9 | <mark>10</mark> 01 |
| 52 | <mark>11</mark> 0100 |
| 6 | <mark>01</mark> 10 |
| 2 | <mark>00</mark> 10 |

Partition on two bits



| Partitions | Number |
|------------|--------|
| 00 | 2 |
| 01 | 6 |
| 10 | 9 |
| 11 | 25, 52 |

Adaptive the reorganization Effort

How much to actually partition?

Processing the First Query

Done out of place, copies the source column into a new array **Option 1**: Using classical approach, copy the column and crack in 2.

If we are copying the entire column anyway, can we do something smarter?

Option 2: Use the efficient radix based method with custom fan-out.

1. Count values in each partition

2. Create a histogram

Input: Source column and K = 2^hb (number of partitions).

3. Use the histogram to initialize pointers to fill the partitions 4. Copy values from the source column to the output column



Translation Lookaside Buffer (TLB)

TLB stores a **mapping** of virtual memory to physical memory for quick lookups.

Separate entry for each partitions.

TLB can only store upto 32 PTEs at a time for huge pages.

How do we handle TLB misses? -Software managed buffers!



Software Managed Buffers



Out of place partitioning using software managed buffers

Buffer of size 2 for each partition

Likely to fit in CPU caches

Non temporal Streaming Stores and SIMD



Enhancing software managed buffers using non temporal streaming stores

SIMD intrinsics allow to bypass the CPU caches when flushing the software-managed buffers to the destination partitions.

Data Partitioning in Subsequent Queries

Already used out of place partitioning for the first query

In place reorganization must happen for subsequent queries

In-place radix partitioning

Step 1: Create a histogram for number of entries for each partition k

Step 2: Perform search and replace on the index column

Phase 1: Histogram Generation

Determine the number of partitions **k** and the number of fanout bit **b**

B is the number of bits by which the input should be partitioned K = 2^b (More on this later)



Now we know the boundaries of the partitions (after 3rd, 5th and 6th element!)



Phase 2: Search and Replace



 Check if elements belong to the right partition.

00

01

11

 15 belongs to partition 11. Scan partition 11 and find the first element that does not belong to 11. Swap it with 15

Evaluation of In and out of place Radix Partitioning

• Overhead of partitioning with higher fan-out k decreases with a decrease in partition size.

Driving factor for deciding *b* bits for K = 2^b

- With a decrease in partition size, increase fan-out k. At a sufficiently small size, finish the partition by sorting it as the cost is negligible.
- How to find K?



Adapting the Partitioning Fan–out K= 2^b



Handling Skew

Radix based partitioning cannot handle skewed input distributions well - **Why?**

Solution: Equi-depth partitioning

Not suitable for radix based partitioning - **Why**?

Meta Adaptive Index's Solution: Equi-depth out of place radix partitioning algo



Skewed Distribution

Equi-depth Distribution

Handling Skew

- Create a histogram for the first query (b= bfirst)
- Skewtol denotes skew tolerance of a partition. If s > (columnsize/k)*skewtol, mark partition as skewed.
- Complete out-of place partitions (*bfirst*) and build histograms on skewed partitions (*bmin*)
- Sub-partition skewed partitons (*bmin*) in-place.



Experimental Evaluation

Two Tests

Emulation of other indexes by meta-adaptive index

Comparison of response times of the meta-adaptive index to other indexes

Emulation of the below Indexing Algorithms

- 1. Standard Cracking
- 2. Hybrid Crack Sort (HCS)
- 3. Hybrid Sort Sort (HSS)
- 4. Scan
- 5. Quick Sort + Binary Search
- 6. Coarse-granular Index 1K

Memory Requirements for the Experiment

32KB of L1 cache

256KB of L2 cache

10MB of shared L3 cache

2MB Page Size

24GB of DDR3 RAM

Our Dataset

100 million entries

Each entry - 8B Key and 8B rowID

1.5 GB of data









What is the effect of differing key distributions?



Different key distributions affect the SKEW



Blue dots represent the high keys whereas red dots represent the low keys



Blue dots represent the high keys whereas red dots represent the low keys



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$$f(s,q) = \begin{cases} b_{first} & \text{if } q = 0\\ b_{min} & \text{else if } s > t_{adapt} \\ b_{min} + \left\lceil (b_{max} - b_{min}) \cdot \left(1 - \frac{s}{t_{adapt}}\right) \right\rceil & \text{else if } s > t_{sort} \\ b_{sort} & \text{else.} \end{cases}$$

Question

From the graph, why is Hybrid Crack Sort and Hybrid Sort Sort better than Standard Cracking?



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Question

In emulation of Scan (blue graph), all parameters are set to 0. So no partitions are created. Still the graph is a line at y = 1. Why?



Question

Can you guess the parameters (b_{first}, b_{min}, t_{adapt}, b_{max}, t_{sort}) for emulation of Coarse-granular Index 1K?



$$f(s,q) = \begin{cases} b_{first} & \text{if } q = 0\\ b_{min} & \text{else if } s > t_{adapt} \\ b_{min} + \left\lceil (b_{max} - b_{min}) \cdot \left(1 - \frac{s}{t_{adapt}}\right) \right\rceil & \text{else if } s > t_{sort} \\ b_{sort} & \text{else.} \end{cases}$$



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Cracking Performance

Crack fails to deliver the performance improvements in sequential workload.

With the sequential workload, Crack touches a large number of tuples, which **falls only negligibly as new queries arrive**, whereas with the random workload the number of touched tuples drops swiftly after only a few queries.



Evaluation of Out-of-place Radix Partitioning

The meta-adaptive index shows the most stable performance and offers early on fast individual response times, similar to the full index.

Question: why does all algos become faster and faster?

The touched tuple become smaller and smaller.



Evaluation of Out-of-place Radix Partitioning

The meta-adaptive index becomes unstable, but still more stable than others.

Question: why does it becomes less stable?

Because many values fall into a narrow range.



Evaluation of Out-of-place Radix Partitioning

The worse case, as most values fall into few partitions. But meta-adaptive index is still the best one.





Accumulated Query Response Time

ne [s]

Query

Accum.

Question: Why does the HCS even slower than DC?



Because HCS is calibrated for sequential queries?? Also, merge is not free.



Conclusion

- 1. Minimal overhead compared to previous work, with better results.
- 2. Performs well in almost every workloads (uniform, normal and zipf distribution).
- 3. Optimize parameters using simulated annealing algorithm.

What can we improve?

- Simulating annealing algorithms has some cons. If the cooling process is slow enough, the performance of more solutions will be better, but in contrast to this, the convergence speed is too slow. If the cooling process is too fast, the global optimal solution may not be obtained.
- 2. **Introduce more adaptive index algorithms** to fully enhanced the robustness of the meta-adaptive index. Also, they could try **MDD1R** stochastic cracking algorithm instead of DD1R.