## Concurrency-Aware Tree/Graph Traversal Algorithms

Randy Collado, Taishan Chen, Yizheng Xie

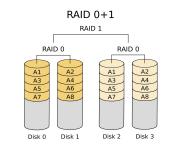
## Background

- Parallelism in data storage
  - Multiple drive: Distributed, RAID
  - Single drive: Solid-State Disk (SSD)

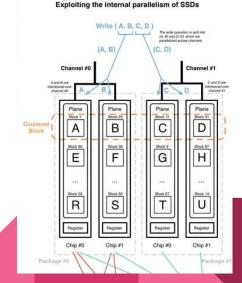
#### • SSD has internal concurrency

- Can handle multiple requests simultaneously
- Serial operations cannot achieve best performance

- Parallel algorithm for data
  - Tree/Graph structure widely used in data and file system
  - Traversal & Searching Algorithms







Coding for SSDs – Part 5: Access Patterns and System Optimizations, Emmanuel Goossaert

## Algorithm - Serial BFS

Breadth-first Search

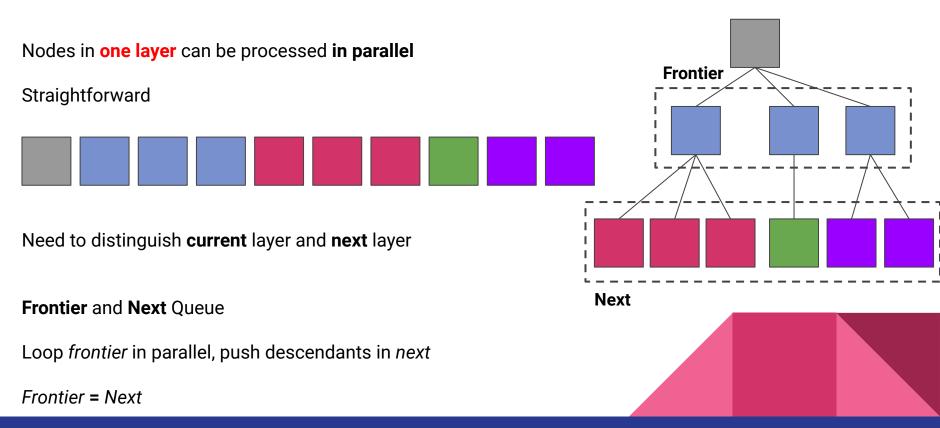
Layer by layer

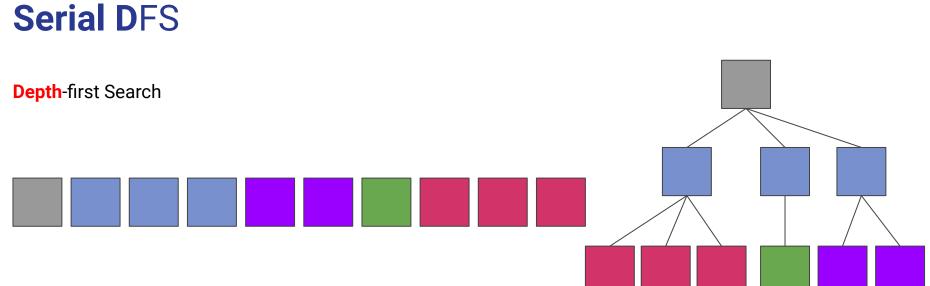
Implement by a queue (FIFO)

Pop\_front() and push\_back() its all descendants









Use Stack (FILO)

Pop\_back() and push\_back()

More common in searching



#### **Parallel D**FS

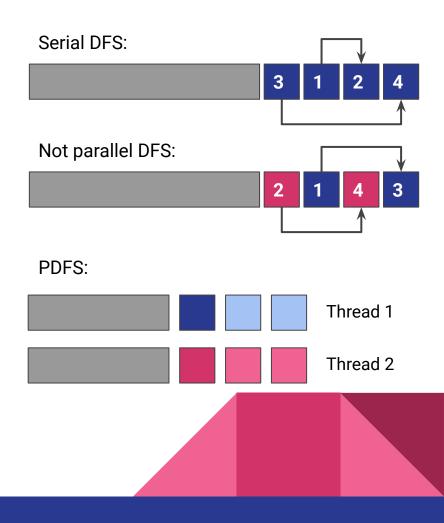
Each processing relies on last result

Both operation are on stack top, have to wait

A strict order DFS cannot be paralleled efficiently

Unordered/Pseudo Parallel DFS: DFS for each thread

Not globally depth-first, but still prefer depth



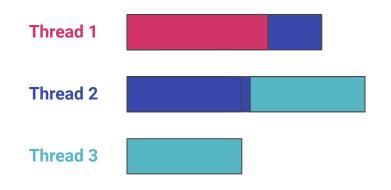
## Parallel DFS - cont.

How to distribute nodes to threads? Keep all threads busy for most parallelism.

- Set a **threshold** size **(fSize)** for stack
- Each thread works on own stack
- When one thread's stack is larger than threshold
  - **Split** into two part
  - $\circ$  Given one part to a **new** thread

We let the OpenMP automatically handle the scheduling. For better performance, control scheduling and balancing.

Acar, Umut A., Arthur Charguéraud, and Mike Rainey. **"A work-efficient algorithm for parallel unordered depth-first search."**, 2015.





#### Code



**OpenMP:** Compiler-level directives, no/minimum changes on codes.

#### Serial and Parallel BFS:

```
std::vector<int> frontier, next;
bool isFound = false;
while (!isFound && frontier.size() > 0):
  for offset in frontier:
    node = read_node(offset);
    if (node.key == key) isFound = true;
    if (isFound || node's children count == 0)
        continue;
    next.insert(node.children);
    frontier = next;
    next.clear();
```

<pre>std::vector<int> frontier, next;</int></pre>
bool isFound = <b>false</b> ;
<mark>#pragma omp parallel</mark>
<pre>while (!isFound &amp;&amp; frontier.size() &gt; 0):</pre>
#pragma omp for nowait
<b>for</b> offset <b>in</b> frontier:
node = <b>read_node</b> (offset);
<pre>if (node.key == key) isFound = true;</pre>
if (isFound    node's children count == 0)
continue;
#pragma omp critical
next. <b>insert</b> (node.children);
frontier = next;
<pre>next.clear();</pre>

#### Code

#### Serial and Parallel DFS:

```
std::vector<int> frontier;
bool isFound = false;
frontier.push_back(0);
while (!frontier.empty()):
   node = read_node(frontier.back());
   if (node.key == key) isFound = true;
   frontier.pop_back();
   frontier.insert(node.children);
return isFound;
```

We also implement IDDFS and some hybrid approach, see code if interested.

```
std::vector<int> frontier;
bool isFound = false;
frontier.push_back(0);
#pragma omp taskgroup
while (!frontier.empty()):
  node = read_node(frontier.back());
  if (node.key == key) isFound = true;
  frontier.pop_back();
  frontier.insert(node.children);
  while (frontier.size() > fSize):
    frontier, frontier_new = frontier.split();
 pragma omp task shared(isFound)
    if (run(frontier_new)) {
      isFound = true:
#pragma omp cancel taskgroup
return isFound;
```

#### **Tree Structure**

- Our testing was conducted on a randomized tree-like graph, with control over its branching factor, the branching factor of the individual nodes, and the number of values allowed per key
- This offers significant flexibility is studying configurations that are beneficial for concurrent search performance
- This also allows us to test worst and best-case scenarios for our search algorithms

#### File Structure

- Memory-mapped structs allow efficient byte-level access of all the data within each node of tree
- Tree is serialized in BFS order, converting each node encountered into an S\_Node, a node format that allows for efficient concurrent access of a node and it's children
- S\_Node structs store the offsets of the children nodes in the file, making the file compatible with both DFS and BFS-based search schemes<sup>1</sup>
- Low-level syscalls allow us to avoid OS intervention and get more accurate results vs. Standard Library

1. Sussenguth, E. H. (1963). Use of tree structures for processing files. Communications of the ACM, 6(5), 272–279. https://doi.org/10.1145/366552.366600

## Serializer and Operators

- File is opened via the open(2) syscall (or CreateFileA on Windows) with the appropriate flags (see Direct I/O)
  - The file descriptor is stored in the serializer object for reading from and writing to the file.
- Operators:
  - **S\_Node\* readNode()**: reads node at current fd position
  - S\_Node\* readNodefromOffset(size\_t offset): reads node at position offset bytes forward relative to start of file
  - void writeNodeWithOffset(size\_t offset): writes node at position offset bytes forward relative to start of file
  - void write\_offset\_metadata(): unused
  - void read\_offset\_metadata(): unused



```
struct S_Node {
   int key;
   int numChildren;
   int payload[8];
   int children[8];
__attribute((aligned(512)));
```

struct Node { size\_t numChildren; size\_t maxChildren; size\_t numValues; size\_t maxValues; int values[8]; Node\* children[8]; }



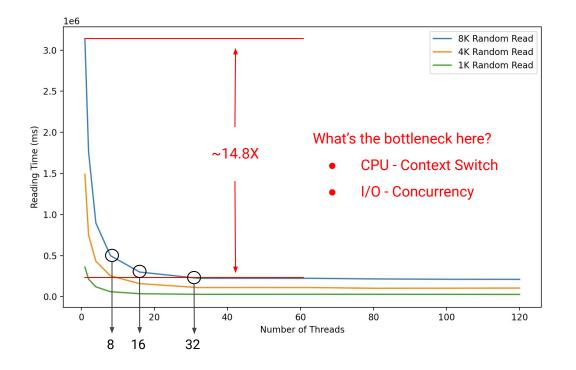
No caching: Test concurrency of storage

Concurrent: I/O operations should not be serialized by OS somehow

No universal libs for now, have to use system calls.

- SSD device which supports concurrent I/O
- O\_DIRECT, pread/pwrite (Linux)
  - Windows: FILE\_FLAG\_NO\_BUFFERING, FILE\_FLAG\_OVERLAPPED, GetOverlappedResult()
- Read/write with offsets

#### Experiments - Direct I/O (Random Read)



#### **Experimental Setting: 8-CPU**

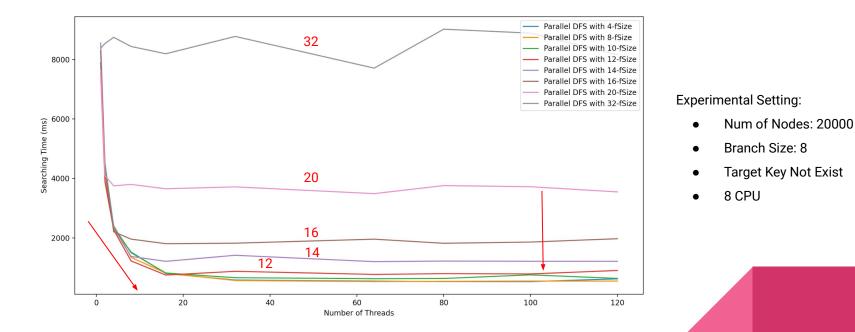
omp set num threads

Summary The omp\_set\_num\_threads routine affects the number of threads to be used for subsequent parallel regions that do not specify a num\_threads clause, by setting the value of the first element of the *nthreads-var* ICV of the current task.

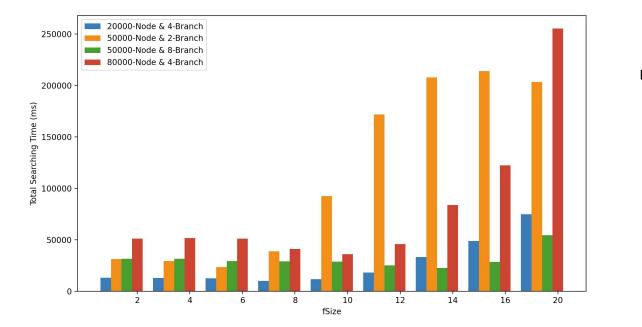
#### Format



#### Experiments - Tuning fSize (Target Key Not Exist)



## Experiments - Tuning fSize (Random Target Key)



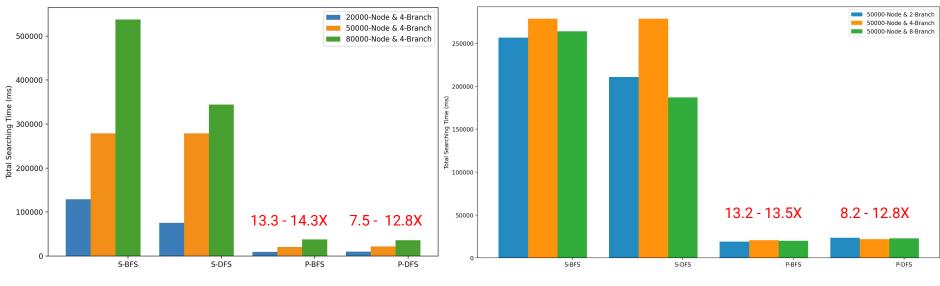
#### **Experimental Setting:**

- Num of Nodes: 20000/50000/80000
- Branch Size: 2/4/8
- 20 Random Target Key + 1 Not Exist
- 8 CPU & 32 Threads

## **Experiments - Algorithm Efficiency**

**Experimental Setting:** 

- 20 Random Target Key + 1 Not Exist
- 8 CPU & 32 Threads



Change Num of Nodes

**Change Branch Size** 

#### **Future Works**

- Algorithm
  - Better controls over scheduling and task stealing
  - Hybrid search, adjust parameters automatically
  - Extend algorithm to general graph structures
- Testing
  - More different workload
  - I/O Matrices like IOPS



#### Some Lessons!

- Try and choose way of implementation wisely.
  - Go: chan, operator(<-, ->)
  - C/C++: Std::thread, OpenMP
- Test in correct way.
  - All tests in memory before midterm, no performance gain, puzzled.
- Leave time for debugging!
  - especially for concurrent programming...



# Thanks!

#### Reference

Acar, U. A., Charguéraud, A., & Rainey, M. (2015, November). A work-efficient algorithm for parallel unordered depth-first search. In Proceedings of the International Conference for High Performance Computing, Networking, Storage and Analysis (pp. 1-12).

Korf, R. E. (1986). Depth-first iterative-deepening: An optimal admissible tree search. Artificial Intelligence, 28(1), 123. <u>https://doi.org/10.1016/0004-3702(86)90035-4</u>

Sussenguth, E. H. (1963). Use of tree structures for processing files. Communications of the ACM, 6(5), 272–279. https://doi.org/10.1145/366552.366600

