

# UpBit: Scalable In-Memory Updatable Bitmap Indexing

# Contents

- Basic bitmap indexing
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- Update-Conscious Bitmap
- UpBit
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# Basic Bitmap Index

	A=1	A=2	A=3
A			
1	1	0	0
3	0	0	1
2	0	1	0
1	1	0	0
2	0	1	0
2	0	1	0
3	0	0	1
3	0	0	1
2	0	1	0

# Basic Bitmap Index

	A=1	A=2	A=3
A			
1	1	0	0
3	0	0	1
2	0	1	0
1	1	0	0
2	0	1	0
2	0	1	0
3	0	0	1
3	0	0	1
2	0	1	0

- Point query
- Range query
- Update
- Append
- Delete

WHERE A=2

A=2
0
0
1
0
1
1
0
0
1

# Basic Bitmap Index

	A=1	A=2	A=3
A			
1	1	0	0
3	0	0	1
2	0	1	0
1	1	0	0
2	0	1	0
2	0	1	0
3	0	0	1
3	0	0	1
2	0	1	0

- Point query
- Range query
- Update
- Append
- Delete

WHERE A<2

	A=1	A=2	
A			
1	1	0	1
0	0	0	0
0	0	1	1
1	1	0	1
0	0	1	1
0	0	1	1
0	0	0	0
0	0	0	1

V =

# Basic Bitmap Index

	A=1	A=2	A=3
A			
1	1	0	0
3	0	0	1
2	0	1	0
1	1	0	0
2	0	1	0
2	0	1	0
3	0	0	1
3	0	0	1
2	0	1	0

- Point query
- Range query
- Update
- Append
- Delete

$A[1] = 2$

	A=2	A=3
1	0	0
3	1	0
2	1	0
0	0	0
1	1	0
1	1	0
0	0	1
0	0	1
1	1	0

# Basic Bitmap Index

	A=1	A=2	A=3
A			
1	1	0	0
3	0	0	1
2	0	1	0
1	1	0	0
2	0	1	0
2	0	1	0
3	0	0	1
3	0	0	1
2	0	1	0

- Point query
- Range query
- Update
- Append
- Delete

Append A=1

	A=1	A=2	A=3
A			
1	1	0	0
3	0	0	1
2	0	1	0
1	1	0	0
2	0	1	0
2	0	0	1
3	0	0	1
3	0	0	1
2	0	1	0
1	1	0	0

# Basic Bitmap Index

	A=1	A=2	A=3
A			
1	1	0	0
3	0	0	1
2	0	1	0
1	1	0	0
2	0	1	0
2	0	1	0
3	0	0	1
3	0	0	1
2	0	1	0

- Point query
- Range query
- Update
- Append
- Delete

Delete A[1]

	A=1	A=2	A=3
A			
1	1	0	0
3	0	0	0
2	0	1	0
1	1	0	0
2	0	1	0
2	0	1	0
3	0	0	1
3	0	0	1
2	0	1	0

# FastBit and WAH

- WAH: word-aligned hybrid
  - Space overhead
    - Data size ↑
    - Cardinality (number of distinct values) ↑

# WAH

- If we have a long range of consecutive bits with the same value, we can compress them

# WAH

Raw bit vector (155 bits)

1	0	0	0	0	1	0	0	0	1	0	1	0	1	0	0	0	0	0	1	0	0	1	1	0	0	1	1	1	0	0	1
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	1	1	0	1	1	1	0	1	1	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0	0	0

# WAH

Raw bit vector (155 bits)

1	0	0	0	0	1	0	0	0	1	0	1	0	1	0	0	0	0	0	1	0	0	1	1	0	0	1	1	1	0	0	1
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
1	1	1	0	1	1	1	0	1	1	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0	0	0

31 bits

# WAH

- Encoded bit vector are partitioned into 32-bit words
  - Literal word
    - | 0 | 31-bit raw bitmap |
  - Fill word
    - | 1 | 1-bit fill bit | # of 31-bit raw bitmap filled with the fill bit |

# WAH

Raw bit vector (155 bits)

0	1	0	0	0	1	0	0	0	1	0	1	0	1	0	0	0	0	0	1	0	0	1	1	0	0	1	1	1	0	0	1	
1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0
0	1	1	1	0	1	1	1	0	1	1	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0	0	0



32 bits

# WAH

- Frequent encoding and decoding are inefficient
- Getting the  $i^{\text{th}}$  position will require to decode all bit vectors from start to the  $i^{\text{th}}$  position
- Query/update will need to encode the entire bit vector

# Update-Conscious Bitmap (UCB)

index

	A	A=1	A=2	A=3	EB
1	1	1	0	0	1
2	3	0	0	1	1
3	2	0	1	0	1
4	1	1	0	0	1
5	2	0	1	0	1
6	2	0	1	0	1
7	3	0	0	1	1
8	3	0	0	1	1
9	2	0	1	0	1

# UCB (query)

WHERE A<2

index

	A	A=1	A=2	A=3	EB
1	1	1	0	0	1
2	3	0	0	1	1
3	2	0	1	0	1
4	1	1	0	0	1
5	2	0	1	0	1
6	2	0	1	0	1
7	3	0	0	1	1
8	3	0	0	1	1
9	2	0	1	0	1

A=1	A=2	EB	
1	0	1	1
0	0	1	0
0	1	1	1
1	0	1	1
0	1	1	1
0	1	1	1
0	0	1	0
0	0	1	1
0	1	1	1

v

$\wedge$

=

# UCB (efficient deletion)

index

	A	A=1	A=2	A=3	EB
1	1	1	0	0	1
2	3	0	0	1	1
3	2	0	1	0	1
4	1	1	0	0	1
5	2	0	1	0	1
6	2	0	1	0	1
7	3	0	0	1	1
8	3	0	0	1	1
9	2	0	1	0	1

index

	A	A=1	A=2	A=3	EB
1	1	1	0	0	1
2	3	0	0	1	0
3	4	1	0	1	1
4	5	2	1	0	0
5	6	2	0	1	1
6	7	3	0	0	1
7	8	3	0	0	1
8	9	2	0	1	0
9					1

# UCB (update)

index

	A	A=1	A=2	A=3	EB
1	1	1	0	0	1
2	3	0	0	1	1
3	2	0	1	0	1
4	1	1	0	0	1
5	2	0	1	0	1
6	2	0	1	0	1
7	3	0	0	1	1
8	3	0	0	1	1
9	2	0	1	0	1

index

	A	A=1	A=2	A=3	EB
1	1	1	0	0	1
2	3	0	0	1	0
3	4	2	1	0	1
4	5	2	1	0	0
5	6	2	0	1	1
6	7	3	0	0	1
7	8	3	0	0	1
8	9	2	0	1	0
9	2	2	1	0	1

# UCB

- When the number of updates goes up
  - The compressibility of the EB goes down
  - When reading, the time needed to decoding and re-encoding goes up
- Therefore, It is not very scalable

# Updatable Bitmap (UpBit)

- The compressibility of the EB goes down when the number of updates goes up
  - UpBit introduces one update bit vector (UB) for each value bit vector (VB), and UB is merged to VB periodically to decrease the compressibility of UB
- Decoding and re-encoding is inefficient when updating and reading
  - UpBit adds fence pointers to compressed VB to enable partial decoding

# Notations

- An attribute  $A$
- $d$  unique values
- $VB = \{V_i \mid \forall i \in \{1, \dots, d\}\}$
- $UB = \{U_i \mid \forall i \in \{1, \dots, d\}\}$

# The internals of UpBit

Base Data		UpBit Index						
rid	Column A	rid	10 VB	10 UB	20 VB	20 UB	30 VB	30 UB
1	30	1	0	0	0	0	1	0
2	20	2	0	0	1	0	0	0
3	30	3	0	0	0	0	1	0
4	10	4	1	0	0	0	0	0
5	20	5	0	0	1	0	0	0
6	10	6	1	0	0	0	0	0
7	30	7	0	0	0	0	1	0
8	20	8	0	0	1	0	0	0

build index  
→

# The internals of UpBit

- Value-Bitvector Mapping
- Update Bitvectors

# UpBit Operations (Retrieving the value of a row )

**get\_value (index: *UpBit*, row: *k*)**

---

```
1: for each i  $\in \{1, 2, \dots, d\}$  do
2:   temp_bit =  $V_i.\text{get\_bit}(k) \oplus U_i.\text{get\_bit}(k)$ 
3:   if temp_bit then
4:     Return vali
5:   end if
6: end for
```

---

**Algorithm 3:** Get value of row *k* using UpBit.

# UpBit Operations (Get a bit in a particular row )

## **get\_bit (bitvector: $B$ , row: $k$ )**

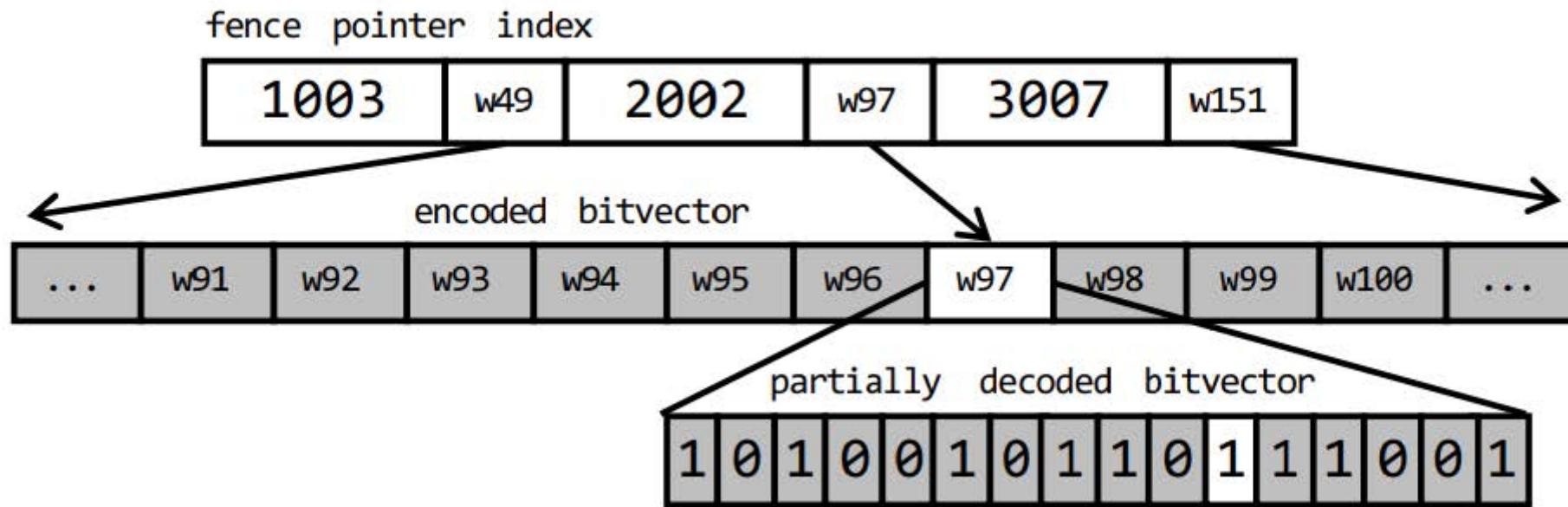
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```
1: pos = fence_pointer.nearest( $k$ )
2: while pos <  $k$  do
3:   if isFill( $B[pos]$ ) then
4:     value, length = decode( $B[pos]$ )
5:     if ( $pos + length$ ) * 31 <  $k$  then
6:       pos += length
7:     else
8:       Return value
9:     end if
10:   else
11:     if pos * 31 -  $k$  < 31 then
12:       Return  $B[pos] \& (1 << (k \% 31))$ 
13:     else
14:       pos ++
15:     end if
16:   end if
17: end while
```

---

**Algorithm 4:** Get  $k_{th}$  bit of a bitvector using UpBit.

# UpBit Operation (Make use of the fence pointers)



# UpBit Operations (Searching)

**search (index: *UpBit*, value: *val*)**

---

- 1: Find the  $i$  bitvector that  $val$  corresponds to
  - 2: **if**  $U_i$  contains only zero **then**
  - 3:     return  $V_i$
  - 4: **else**
  - 5:     return  $V_i \oplus U_i$
  - 6: **end if**
- 

**Algorithm 1:** Searching UpBit for value  $val$ .

# UpBit Operations (Searching)

rid	10		20		30		Updated
	VB	UB	VB	UB	VB	UB	
1	0	0	0	0	1	0	0
2	0	1	1	1	0	0	0
3	0	0	0	0	1	0	0
4	1	0	0	0	0	0	0
5	0	0	1	0	0	0	0
6	1	0	0	0	0	0	0
7	0	0	0	0	1	0	0
8	0	0	1	0	0	0	1

probe A=20 →

$\oplus =$

rid	VB	UB	Updated
1	0	0	0
2	1	1	0
3	0	0	0
4	0	0	0
5	1	0	1
6	0	0	0
7	0	0	0
8	1	0	1

# UpBit Operations (Deleting)

**delete\_row (index: UpBit, row: k)**

---

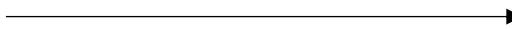
- 1: Find the  $val$  of row  $k$
  - 2: Find the  $i$  bitvector that  $val$  corresponds to
  - 3:  $U_i[k] = \neg U_i[k]$
- 

**Algorithm 2:** Deleting row  $k$  with UpBit.

# UpBit Operations (Deleting)

rid	10		20		30	
	VB	UB	VB	UB	VB	UB
1	0	0	0	0	1	0
2	0	0	1	0	0	0
3	0	0	0	0	1	0
4	1	0	0	0	0	0
5	0	0	1	0	0	0
6	1	0	0	0	0	0
7	0	0	0	0	1	0
8	0	0	1	0	0	0
Pad	0	0	0	0	0	0

Delete row 2



rid	10		20		30	
	VB	UB	VB	UB	VB	UB
1	0	0	0	0	1	0
2	0	0	1	1	0	0
3	0	0	0	0	1	0
4	1	0	0	0	0	0
5	0	0	1	0	0	0
6	1	0	0	0	0	0
7	0	0	0	0	1	0
8	0	0	1	0	0	0
Pad	0	0	0	0	0	0

# UpBit Operations (Updating)

## **update\_row** (**index**: *UpBit*, **row**: *k*, **value**: *val*)

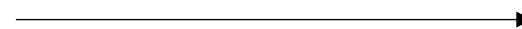
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- 1: Find the *i* bitvector that *val* corresponds to
  - 2: Find the old value *old\_val* of row *k*
  - 3: Find the *j* bitvector that *old\_val* corresponds to
  - 4:  $U_i[k] = \neg U_i[k]$
  - 5:  $U_j[k] = \neg U_j[k]$
-

# UpBit Operations (Updating)

rid	10		20		30	
	VB	UB	VB	UB	VB	UB
1	0	0	0	0	1	0
2	0	0	1	0	0	0
3	0	0	0	0	1	0
4	1	0	0	0	0	0
5	0	0	1	0	0	0
6	1	0	0	0	0	0
7	0	0	0	0	1	0
8	0	0	1	0	0	0
Pad	0	0	0	0	0	0

Update row 2 from 20 to 10



rid	10		20		30	
	VB	UB	VB	UB	VB	UB
1	0	0	0	0	1	0
2	0	1	1	1	0	0
3	0	0	0	0	0	1
4	1	0	0	0	0	0
5	0	0	1	0	0	0
6	1	0	0	0	0	0
7	0	0	0	0	0	1
8	0	0	1	0	0	0
Pad	0	0	0	0	0	0

# UpBit Operations (Inserting)

## **insert\_row (index: *UpBit*, value: *val*)**

---

- 1: Find the  $i$  bitvector that  $val$  corresponds
  - 2: **if**  $U_i$  does not have enough empty padding space **then**
  - 3:   Extend  $U_i$  padding space
  - 4: **end if**
  - 5:  $U_i.\#elements++$
  - 6:  $U_i[\#elements] = 1$
- 

**Algorithm 6:** Insert new value,  $val$ .

# UpBit Operations (Inserting)

rid	10		20		30	
	VB	UB	VB	UB	VB	UB
1	0	0	0	0	1	0
2	0	0	1	0	0	0
3	0	0	0	0	1	0
4	1	0	0	0	0	0
5	0	0	1	0	0	0
6	1	0	0	0	0	0
7	0	0	0	0	1	0
8	0	0	1	0	0	0
Pad	0	0	0	0	0	0

Update row 2 from 20 to 10



rid	10		20		30	
	VB	UB	VB	UB	VB	UB
1	0	0	0	0	1	0
2	0	0	1	0	0	0
3	0	0	0	0	0	1
4	1	0	0	0	0	0
5	0	0	1	0	0	0
6	1	0	0	0	0	0
7	0	0	0	0	0	1
8	0	0	1	0	0	0
9	0	0	1	0	0	0

# UpBit Operations (Merging)

**merge (index: UpBit, bitvector:  $i$ )**

---

```
1:  $V_i = V_i \oplus U_i$ 
2:  $comp\_pos = 0$ 
3:  $uncomp\_pos = 0$ 
4:  $last\_uncomp\_pos = 0$ 
5: for each  $i \in \{1, 2, \dots, length(V_i)\}$  do
6:   if  $isFill(V_i[pos])$  then
7:      $value, length += decode(V_i[pos])$ 
8:      $uncomp\_pos += length$ 
9:   else
10:     $uncomp\_pos ++$ 
11:   end if
12:   if  $uncomp\_pos - last\_uncomp\_pos > THRESHOLD$  then
13:      $FP.append(comp\_pos, uncomp\_pos)$ 
14:      $last\_uncomp\_pos = uncomp\_pos$ 
15:   end if
16:    $comp\_pos ++$ 
17: end for
18:  $U_i \leftarrow 0s$ 
```

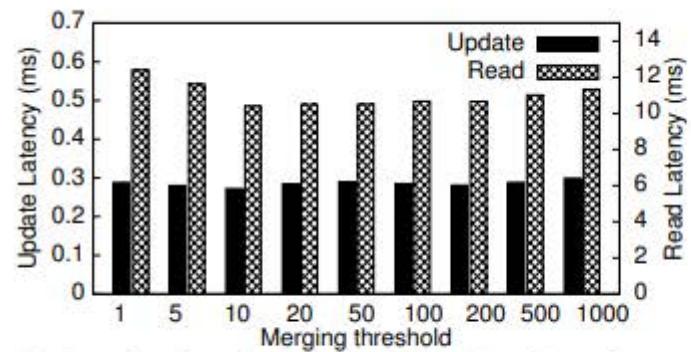
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**Algorithm 7:** Merge UB of bitvector  $i$ .

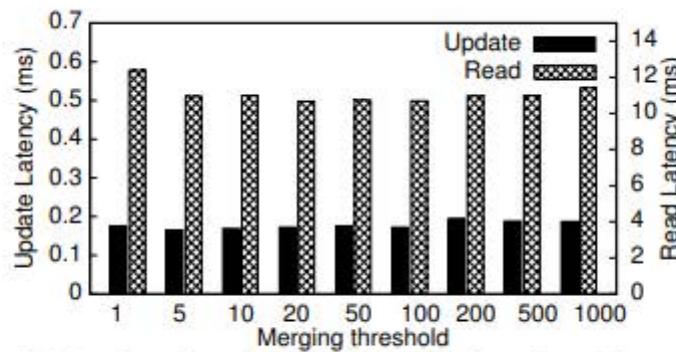
# Tuning UpBit

- The UB-VB merging threshold
- The fence pointer granularity
- The level of parallelism used

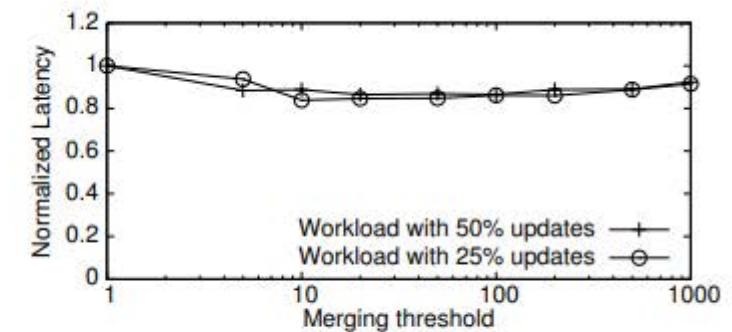
# Tuning UpBit (merging threshold)



(a) Read and update latency as a function of merging threshold for a workload with 20% updates.



(b) Read and update latency as a function of merging threshold for a workload with 50% updates.



(c) Merging threshold for the overall workload combining reads and updates.

# Tuning UpBit (fence pointers granularity)

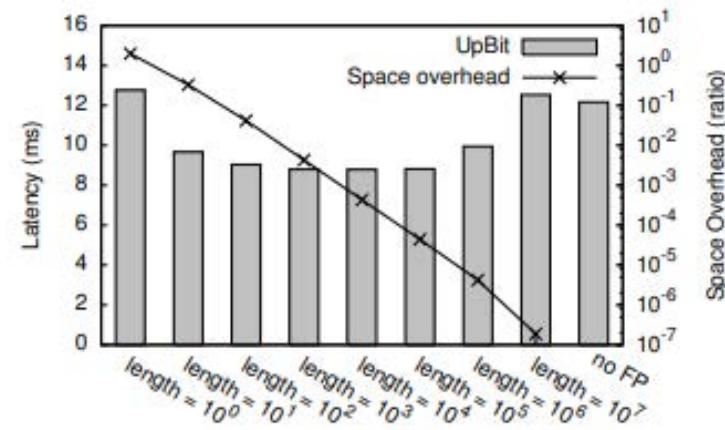


Figure 20: UpBit’s optimal behavior needs fence pointers every  $10^3\text{-}10^5$  values having less than 0.5% space overhead.

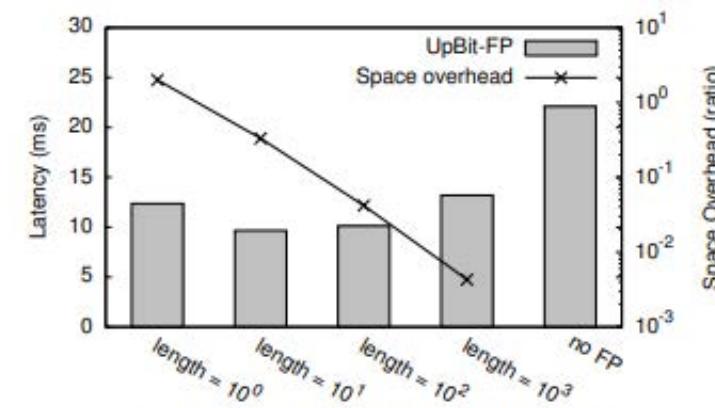


Figure 23: Fence pointers alone offer more than 2 $\times$  better performance, having less than 10% space overhead.

# Tuning UpBit (# of parallelism)

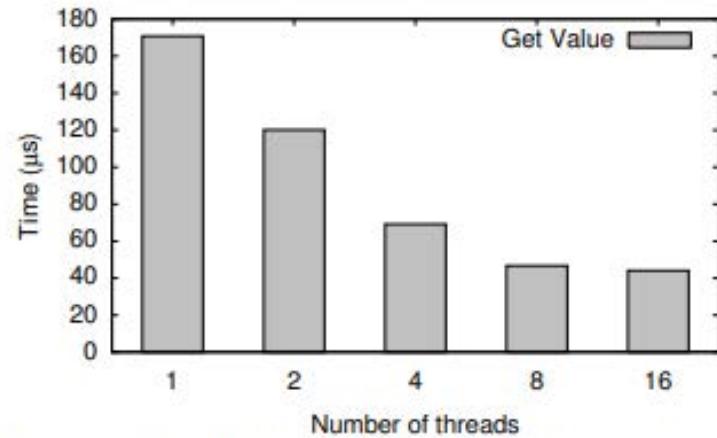


Figure 21: Bitvectors parallel scans scale with number of threads, leading to  $3.9\times$  improvement in *get\_value*.

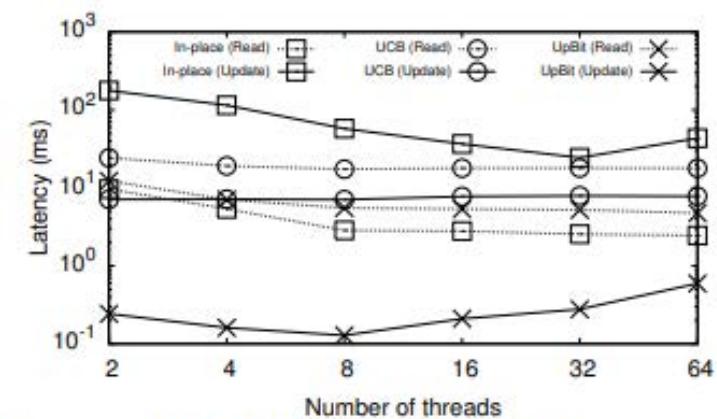


Figure 22: Updates with UpBit are two orders of magnitude faster than other approaches and scale for up to 8 threads.

# Performance and conclusion

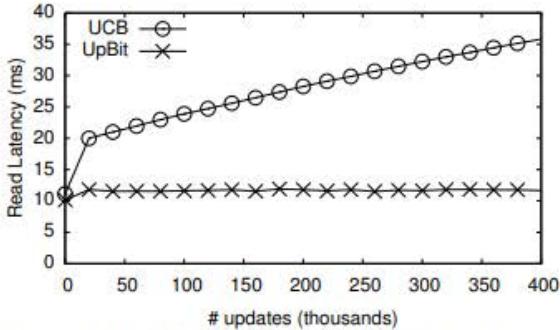


Figure 9: When stressing UpBit with updates, it delivers scalable read performance, addressing the most important limitation observed for UCB.

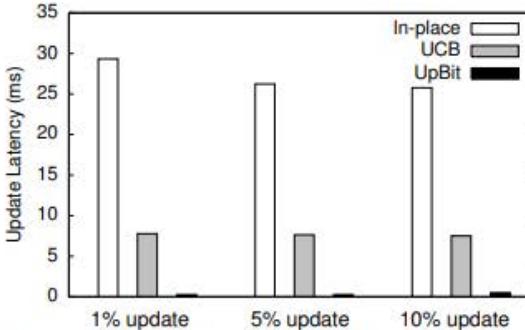


Figure 10: UpBit delivers 51 – 115× faster updates than in-place updates and 15 – 29× faster updates than state-of-the-art update-optimized bitmap index UCB.

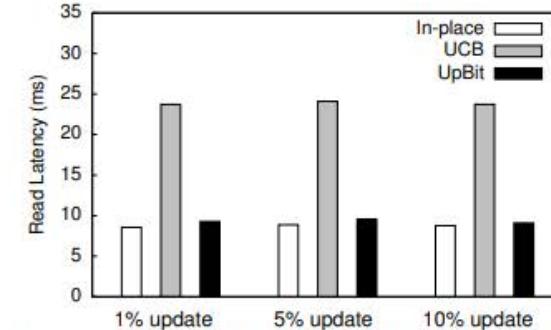
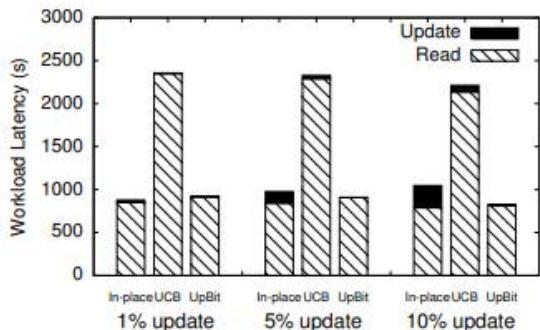
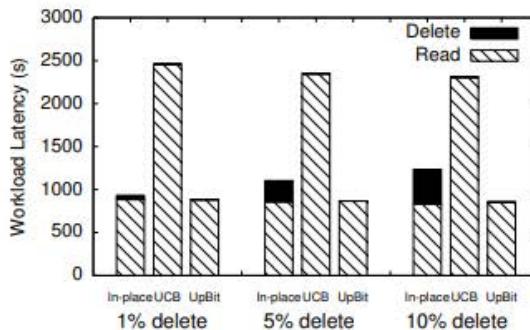


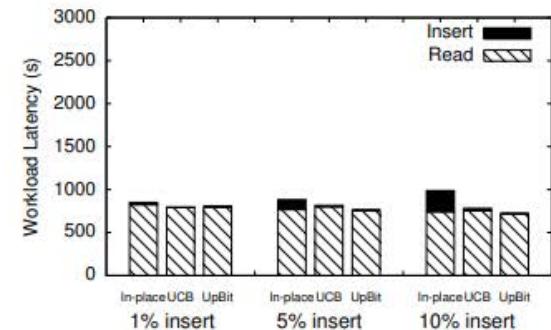
Figure 11: UpBit outperforms update-optimized indexes by nearly 3× in terms of read performance while it loses only 8% compared to read-optimized indexes.



(a) UpBit vs. UCB vs. in-place for updates.



(b) UpBit vs. UCB vs. in-place for deletes.



(c) UpBit vs. UCB vs. in-place for inserts.

Figure 12: As we vary the percentage of updates, deletes or inserts from 1% to 10%, UpBit has the lowest overall workload latency when compared with any other setup. UpBit achieves similar read performance to a read-optimized bitmap index and drastically better updates (a) and deletes (b) than both read-optimized and update-optimized indexes. When inserting new values (c) all approaches have a similar low overhead on read performance. In-place updates cannot gradually absorb the new values, hence, inserting cost does not scale.

# Performance and conclusion

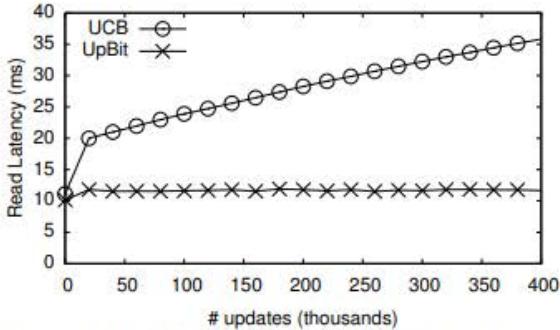


Figure 9: When stressing UpBit with updates, it delivers scalable read performance, addressing the most important limitation observed for UCB.

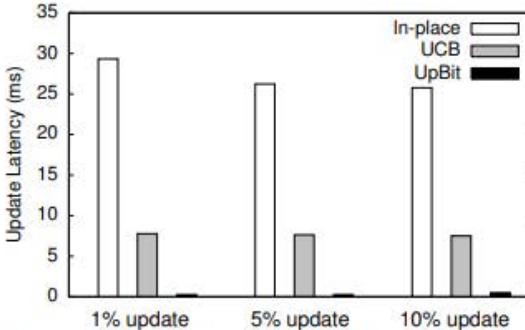


Figure 10: UpBit delivers 51 – 115× faster updates than in-place updates and 15 – 29× faster updates than state-of-the-art update-optimized bitmap index UCB.

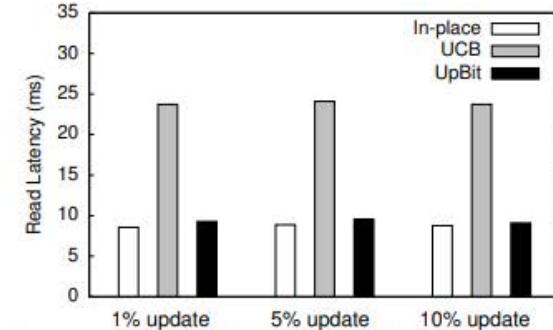
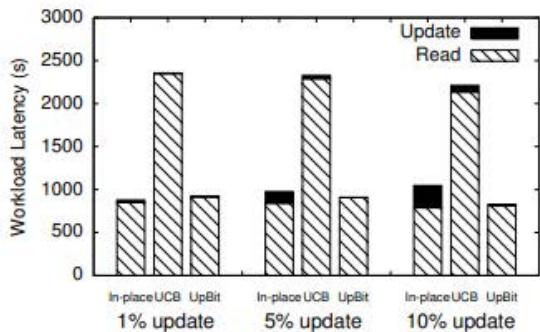
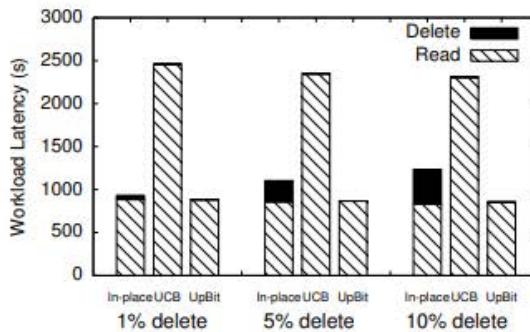


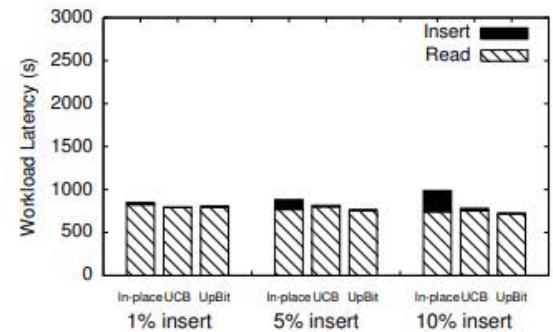
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# Performance and conclusion

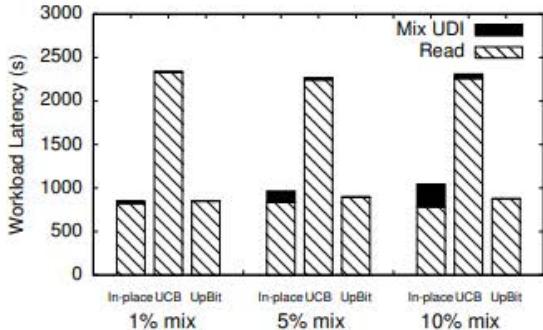


Figure 13: For general UDI workload, the overhead of maintaining a gradually less compressible EB overwhelms UCB, while UpBit offers faster workload execution than both approaches.

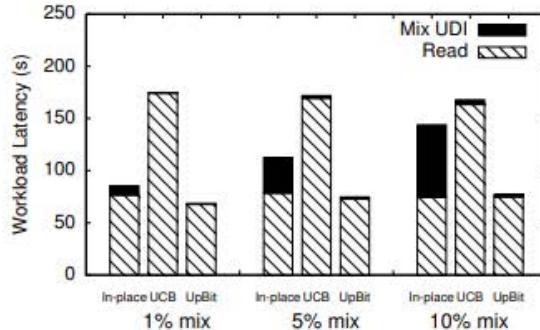


Figure 14: For a data set with larger domain cardinality ( $d = 1000$ ) the update cost is relatively higher, and UpBit has a bigger benefit over in-place updates for the same number of updates.

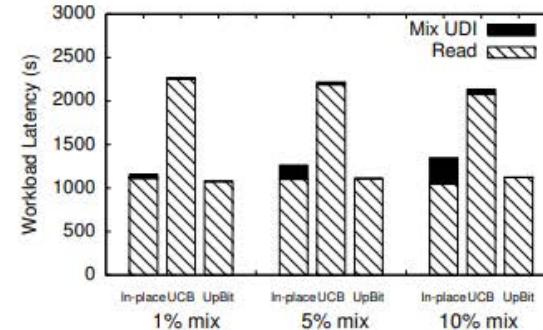


Figure 15: When increasing the data set size ( $n = 1B$ ,  $d = 100$ ), the qualitative behavior of all approaches remain the same. The average latency increases linearly with the data set size.

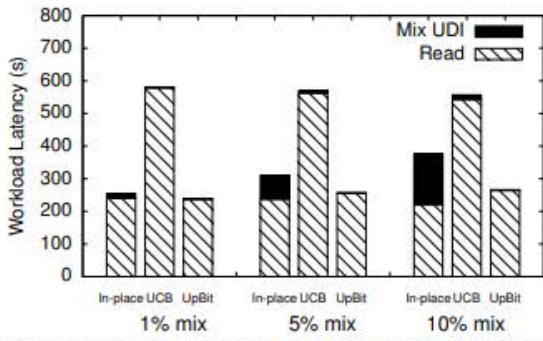


Figure 16: For skewed data (zipfian with  $S = 1.5$ ), the latency decreases as most bitvectors are nearly empty. UpBit faces a small overhead because it has the same distribution of FPs in all VBs.

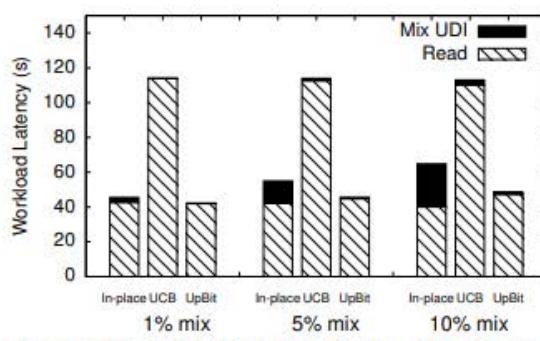


Figure 17: UpBit outperforms all other approaches with real data as well (Berkeley Earth data set with  $n = 31M$  values, and domain cardinality  $d = 114$ ) for a workload with 1%, 5% or 10% updates.

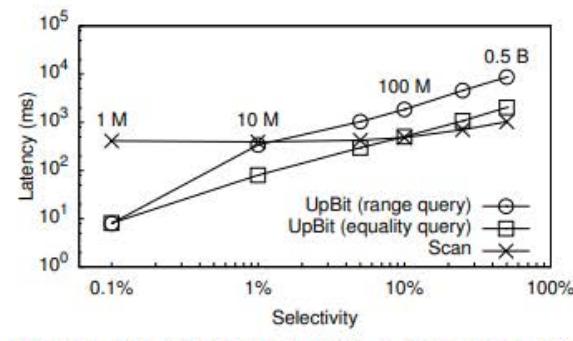


Figure 18: Compared with a fast scan, UpBit is faster for range queries with up to 1% selectivity. Equality queries with similar selectivity are much more efficient because we avoid the bitwise OR between VBs.